**1. Aim of the practical:** Understanding robotics development platform environment to model, program and simulate robots

**2. Tool Used:** CoppeliaSim

**3. Basic Concept/ Command Description:**

Theory of robotics

**4. Observations, Simulation Screen Shots and Discussions:**

**STEPS TO START WITH COPPELIASIM: From LMS**

**Then start with given procedure and take screenshots of each step**











